## Outline

$\square$ Classes of Shared memory systems
$\square$ Types of Interconnection Networks
$\square$ Metrics for Interconnection Networks

## SHARED MEMORY and SHARED VARIABLES

$\square$ Depending on whether 2 or more processors can gain access to the same memory location simultaneously,
$\square$ we have 4 subclasses of shared memory computers

## SHARED MEMORY and SHARED VARIABLES

$\square$ Exclusive Read, Concurrent Write (ERCW) SM Computers
Multiple processors are allowed to write into the same memory location but read access remains exclusive.
$\square$ Concurrent Read, Concurrent Write (CRCW) SM Computers
$\square$ Both multiple read and multiple write privileges are allowed.

## Recap

$\square$ Where there are N processors each with its own individual data stream i.e. SIMD. and MIMD.,
$\square$ it is usually necessary to communicate data / results between processors.
$\square$ This can be done in two main ways.
$\square$ Using a SHARED MEMORY and SHARED VARIABLES
$\square$ And using Interconnection Networks.

## SHARED MEMORY and SHARED VARIABLES

$\square$ Exclusive Read, Exclusive Write (EREW) SM Computers
$\square$ Access to memory locations is exclusive i.e. no 2 processors are allowed to simultaneously read from or write into the same location.
$\square$ Concurrent Read, Exclusive Write (CREW) SM Computers
$\square$ Multiple processors are allowed to read from the same location but write is still exclusive. .i.e. no 2 processors are allowed to write into the same location simultaneously

## SHARED MEMORY and SHARED VARIABLES

$\square$ Allowing concurrent read access to the same address should pose no problems ( except perhaps to the result of a calculation)
$\square$ Conceptually, each of the several processors reading from that location makes a copy of its contents and stores it in its own register (RAM)

## SHARED MEMORY and SHARED VARIABLES

$\square$ Problems arise however, with concurrent write access.
$\square$ If several processors are trying to simultaneously store ( potentially different) data at the same address, which of them should succeed ?
$\square$ i.e. we need a deterministic way of specifying the contents of a memory location after a concurrent write operation.

## SHARED MEMORY and SHARED VARIABLES

$\square$ It is only feasible to allow P processors to access P memory locations simultaneously for relatively small P(<30)
$\square$ Usually because of the cost of the communication.

## SHARED MEMORY and SHARED <br> VARIABLES

$\square$ Some ways of resolving write conflicts include :-
$\square$ Assign priorities to the processors and accept value from highest priority processor
$\square$ All the processors are allowed to write, provided that the quantities they are attempting to store are equal, otherwise access is denied to ALL processors.

## Interconnection Networks

$\square$ We have seen that one way for processors to communicate data is to use a shared memory and shared variables.
$\square$ However this is unrealistic for large numbers of processors.
$\square$ A more realistic assumption is that each processor has its own private memory and data communication takes place using message passing via an INTERCONNECTION NETWORK.

## Interconnection Networks

$\square$ The interconnection network plays a central role in determining the overall performance of a multicomputer system.
$\square$ If the network cannot provide adequate performance, for a particular application, nodes will frequently be forced to wait for data to arrive.
$\square$ Some of the more important networks include

## Interconnection Networks

$\square$ Fully connected or all-to-all
Mesh
Rings
Hypercube
X - Tree
$\square$ Shuffle Exchange
Butterfly
Cube Connected Cycles

## Interconnection Networks -dynamic

$\square$ Multi - Stage Interconnection network
$\square$ Cross - Bar Interconnection Network

## Fully connected or all-to-all

$\square$ Each node has $\mathrm{N}-1$ connections ( $\mathrm{N}-1$ nearest neighbours)
$\square$ giving a total of $\mathrm{N}(\mathrm{N}-1) / 2$ connections for the network.
$\square$ Even though this is the best network to have,
$\square$ the high number of connections per node mean this network can only be implemented for small values of N .

## Fully connected or all-to-all

$\square$ This is the most powerful interconnection network ( topology ): each node is directly connected to ALL other nodes.


## Mesh (Torus)

$\square$ In a mesh network, the nodes are arranged in a k dimensional lattice of width $w$, giving a total of $w^{\wedge} k$ nodes.
$\square$ Usually $\mathrm{k}=1$ (linear array) or $\mathrm{k}=2$ (2D array) e.g. ICL DAP.
$\square$ Communication is allowed only between neighbouring nodes.
$\square$ All interior nodes are connected to 2 k other nodes.



## Rings

$\square$ It is equivalent to a 1 D mesh with wraparound connections.
$\square$ One drawback to this network is that some data transfers may require $N / 2$ links to be traversed e.g. $A$ and $B$ above (3).
$\square$ This can be reduced by using a chordal ring
$\square$ This is a simple ring with cross or chordal links between nodes on opposite sides

## Hypercube Connection (Binary nCube )

$\square$ Hypercube networks consist of $\mathrm{N}=2^{\wedge} \mathrm{k}$ nodes
$\square$ arranged in a k dimensional hypercube.
$\square$ The nodes are numbered $0,1, \ldots .2^{\wedge} k-1$
$\square$ and two nodes are connected if their binary labels differ by exactly one bit

## Rings

$\square$ A simple ring is just a linear array with the end nodes linked.


## Rings


E.eg 10 hyperculse ( 2 modes)

E.g-2 2 Sh hpercube ( 4 modes)


E-q 3D hypercube (E modes)



## Metrics for Interconnection Networks

$\square$ Metrics provide a framework to compare and evaluate interconnection networks.
$\square$ The main metrics are:

- Network connectivity
- Network diameter
- Narrowness
$\square$ Network expansion increments

Hypercube Connection (Binary nCube )
$\square \mathrm{K}$ dimensional hypercube is formed by combining two k-1 dimensional hypercubes and connecting corresponding nodes i.e. hypercubes are recursive.
each node is connected to $k$ other nodes i.e. each is of degree $k$

## Network Connectivity

$\square$ Network nodes and communication links sometimes fail and must be removed from service for repair.
$\square$ When components do fail the network should continue to function with reduced capacity.
$\square$ Network connectivity measures the resiliency of a network and
$\square$ its ability to continue operation despite disabled components

## Network Connectivity

$\square$ i.e. connectivity is the minimum number of nodes or links that must fail to partition the network into two or more disjoint networks
$\square$ The larger the connectivity for a network the better the network is able to cope with failures.

## Network Diameter

$\square$ The diameter of a network is the maximum internode distance
$\square$ i.e. it is the maximum number of links that must be traversed to send a message to any node along a shortest path.
$\square$ The lower the diameter of a network the shorter the time to send a message from one node to the node farthest away from it.

## Narrowness

$\square$ This is a measure of congestion in a network and is calculated as follows:
$\square$ Partition the network into two groups of processors $A$ and $B$
$\square$ where the number of processors in each group is Na and Nb and assume $\mathrm{Nb}<=\mathrm{Na}$.
$\square$ Now count the number of interconnections between $A$ and $B$ call this $I$.

## Network Expansion Increments

$\square$ A network should be expandable i.e.
$\square$ it should be possible to create larger and more powerful multicomputer systems by simply adding more nodes to the network.
$\square$ For reasons of cost, it is better to have the option of small increments since this allows you to upgrade your network to the size you require (i.e. flexibility ) within a particular budget.

## Other metrics

$\square$ Bisection bandwidth
$\square$ the speed with which data from two halves of the network can be transposed across an arbitrary cut
$\square$ Cost
$\square$ Proportional to the number of communication links

| Other metrics |
| :--- |
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## Narrowness

$\square$ Find the maximum value of $\mathrm{Nb} / \mathrm{I}$ for all partitionings of the network.
$\square$ This is the narrowness of the network.
$\square$ The idea is that if the narrowness is high ( $\mathrm{Nb}>\mathrm{I}$ ) then if the group $B$ processors want to send messages to group $A$, congestion in the network will be high ( since there are fewer links than processors )

## Network Expansion Increments

$\square$ E.g. an 8 node linear array can be expanded in increments of 1 node but a 3 dimensional hypercube can be expanded only by adding another 3D hypercube. (i.e. 8 nodes)


